

AILA

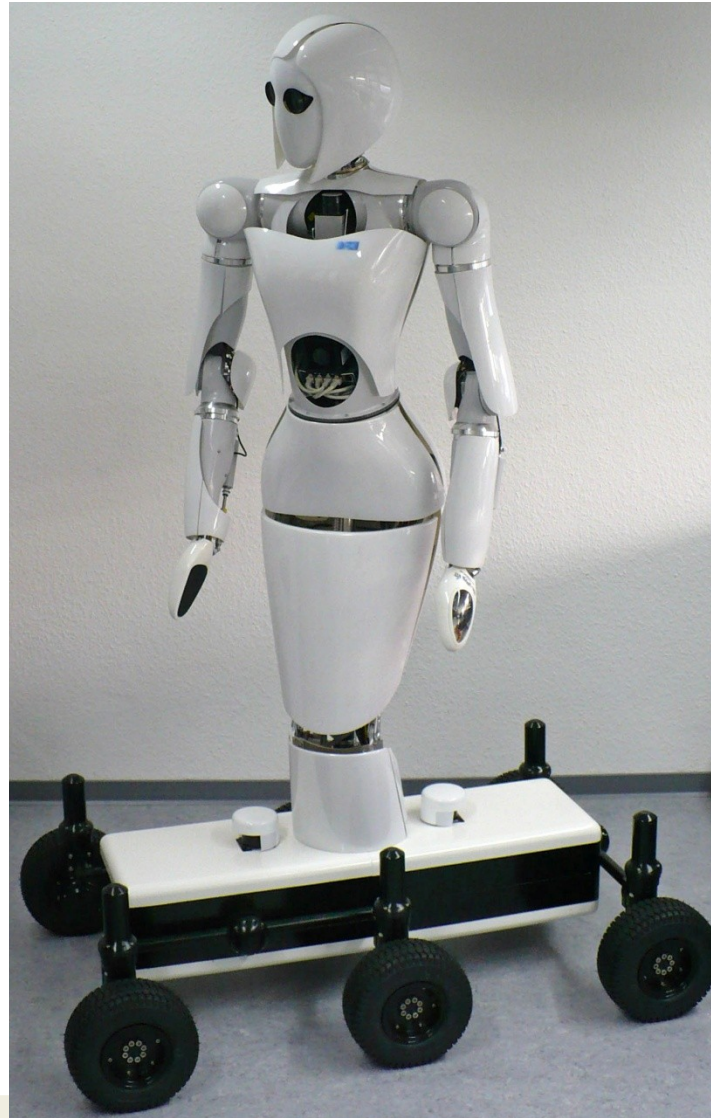
- Towards Autonomous Mobile Manipulation -

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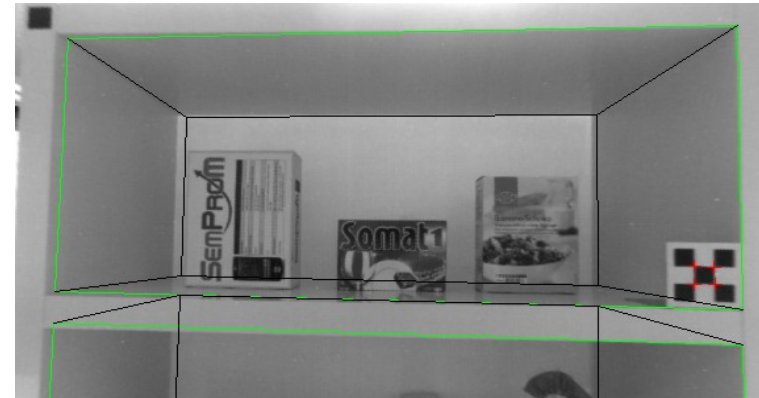


- Scene/Object recognition and pose estimation
- One and two-arm manipulation (trajectory) planning
- Force based grasping/control
- Real-time motion control
- RFID-based task planning
- ROS based Software architecture :
 - interprocess communication
 - task coordination and execution

- Object Recognition based on SIFT Feature Matching



- Marker and Shelf Recognition



- 3D Object's Pose Estimation



Dual-Arm Trajectory Planning



- Planning including 4 torso DOFs (total of 18 DOFs)

