

My Two-Minutes-Presentation

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Symbolic representation of knowledge

...in logically sound models (called ontologies)

...of the robot own believes

...as well as of the other agents the robot interact with.

These models are fed by external modules (geometric reasoning, dialogue...)

...and can be passively queried, or can actively trigger events.

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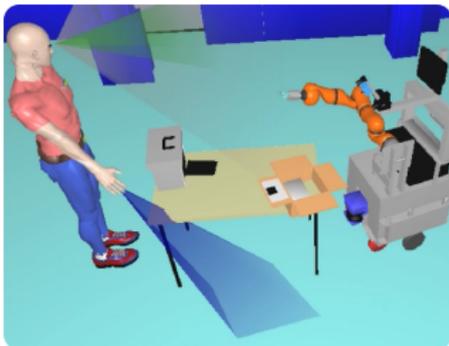
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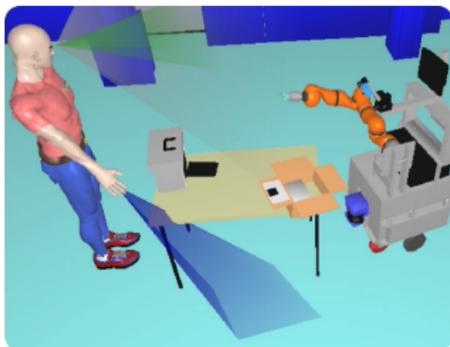
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For what purpose?

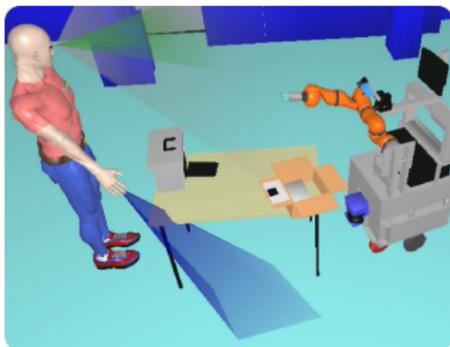


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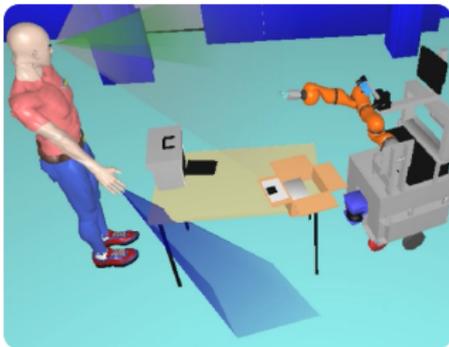
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...[what is "this" ?]...

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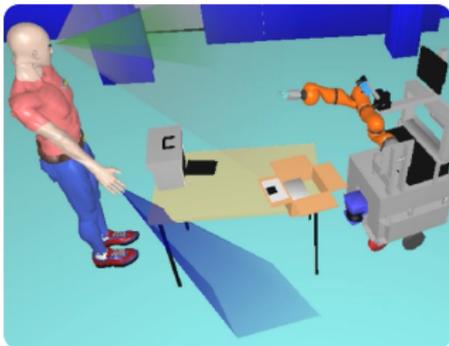
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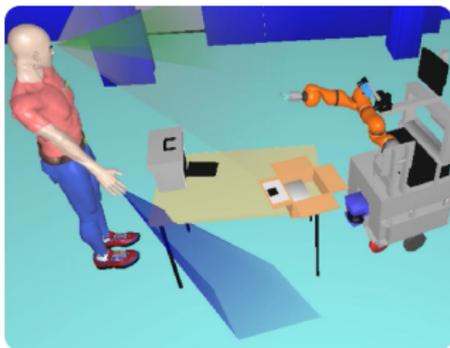
```
human1 desires action1
action1 type Give
action1 performedBy myself
action1 actsOnObject cardboardbox
action1 receivedBy human1
```

For what purpose?



”- Where is the other tape?”

For what purpose?



```
find ?loc /  
?obj type Tape  
?obj differentOf tape1  
?obj isAt ?loc
```

And now, let's hack!